



Shanghai Jiao Tong University





John Hopcroft Center for Computer Science

CS 445: Combinatorics

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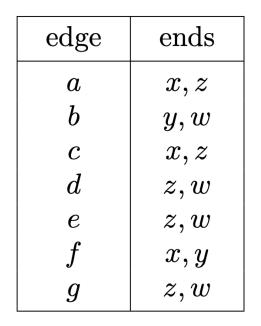
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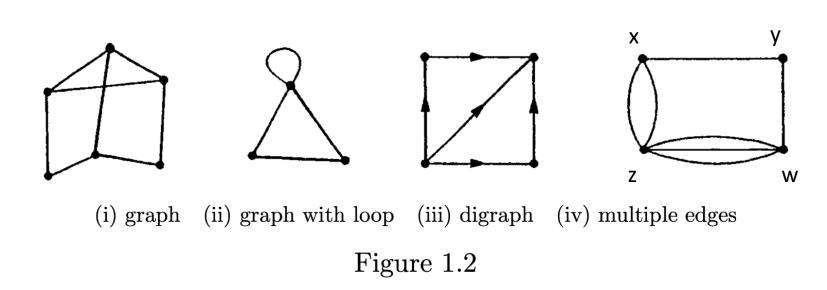
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Basics

Graphs

- Definition A graph G is a pair (V, E)
 - *V*: set of vertices
 - *E*: set of edges
 - $e \in E$ corresponds to a pair of endpoints $x, y \in V$

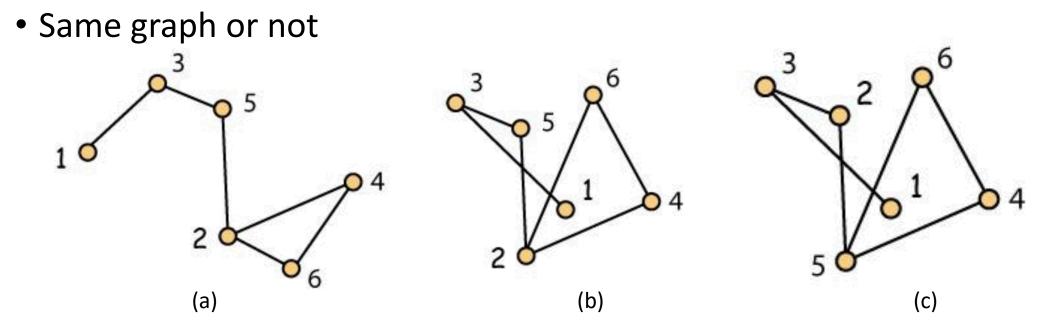




We mainly focus on Simple graph: No loops, no multi-edges

Figure 1.1

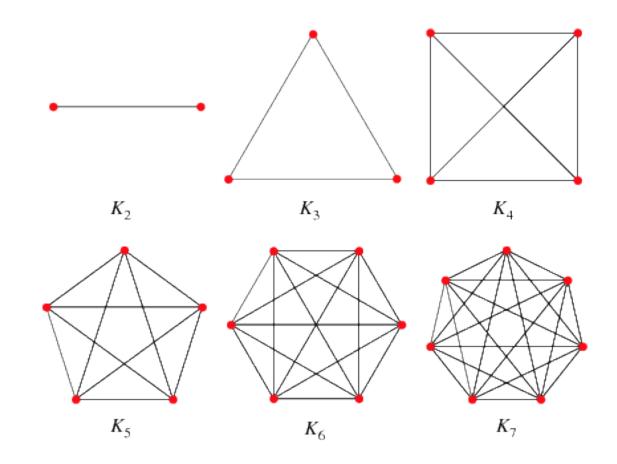
Graphs: All about adjacency



• Two graphs $G_1 = (V_1, E_1), G_1 = (V_2, E_2)$ are isomorphic if there is a bijection $f: V_1 \rightarrow V_2$ s.t. $e = \{a, b\} \in E_1 \iff f(e) := \{f(a), f(b)\} \in E_2$

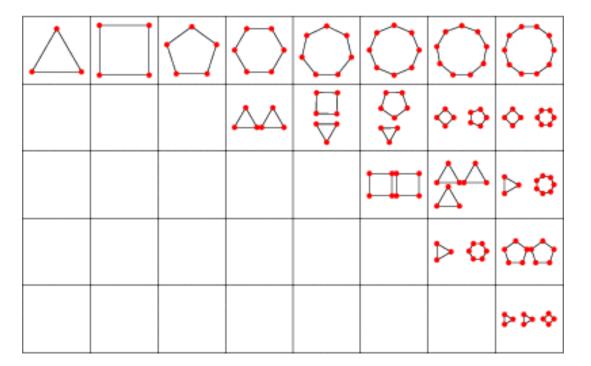
Example: Complete graphs

• There is an edge between every pair of vertices

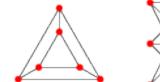


Example: Regular graphs

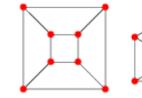
• Every vertex has the same degree







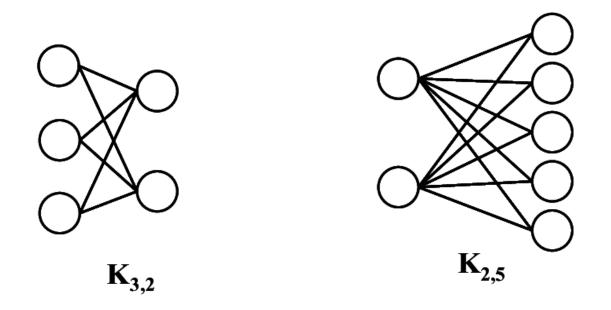






Example: Bipartite graphs

- The vertex set can be partitioned into two sets X and Y such that every edge in G has one end vertex in X and the other in Y
- Complete bipartite graphs



Example (1A, L): Peterson graph

• Show that the following two graphs are same/isomorphic

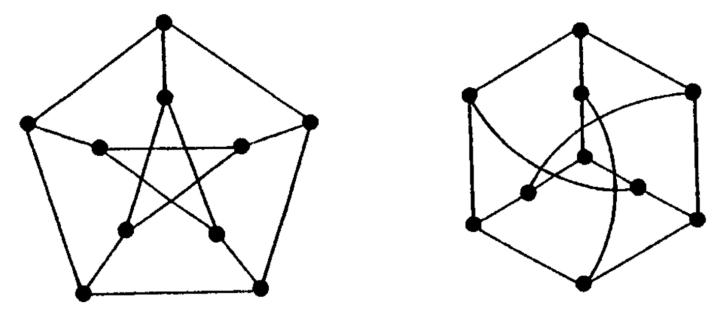
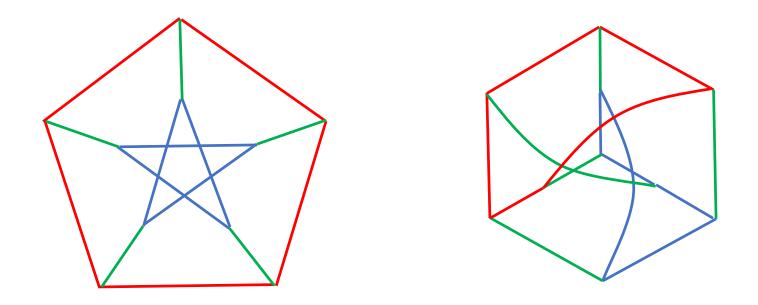


Figure 1.4

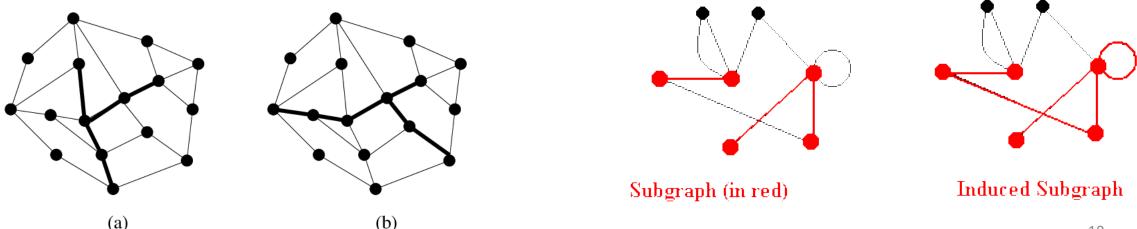
Example: Peterson graph (cont.)

• Show that the following two graphs are same/isomorphic



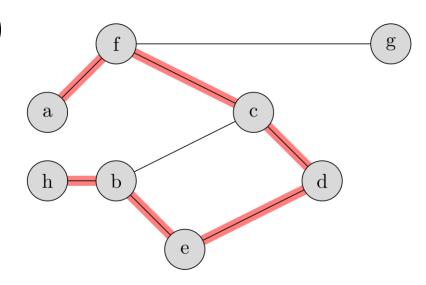
Subgraphs

- A subgraph of a graph G is a graph H such that $V(H) \subseteq V(G), E(H) \subseteq E(G)$ and the ends of an edge $e \in E(H)$ are the same as its ends in G
 - *H* is a spanning subgraph when V(H) = V(G)
 - The subgraph of G induced by a subset $S \subseteq V(G)$ is the subgraph whose vertex set is S and whose edges are all the edges of G with both ends in S



Paths (路径)

- A path is a non-empty alternating sequence $v_0 e_1 v_1 e_2 \dots e_k v_k$ where vertices are all distinct
 - Or it can be written as $v_0v_1 \dots v_k$ in simple graphs
- P^k : path of length k (the number of edges)

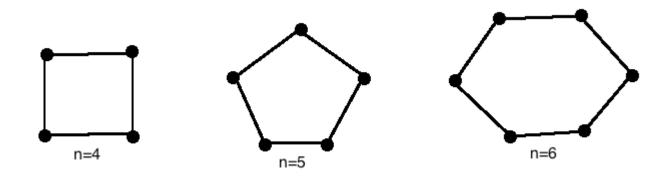


Walk (游走)

- A walk is a non-empty alternating sequence $v_0 e_1 v_1 e_2 \dots e_k v_k$
 - The vertices not necessarily distinct
 - The length = the number of edges
- Proposition (1.2.5, W) Every u-v walk contains a u-v path

Cycles (环)

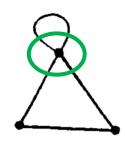
- If $P = x_0 x_1 \dots x_{k-1}$ is a path and $k \ge 3$, then the graph $C \coloneqq P + x_{k-1} x_0$ is called a cycle
- C^k: cycle of length k (the number of edges/vertices)



• Proposition (1.2.15, W) Every closed odd walk contains an odd cycle

Neighbors and degree

- Two vertices $a \neq b$ are called adjacent if they are joined by an edge
 - N(x): set of all vertices adjacent to x
 - neighbors of *x*
 - A vertex is isolated vertex if it has no neighbors
- The number of edges incident with a vertex x is called the degree of x
 - A loop contributes 2 to the degree

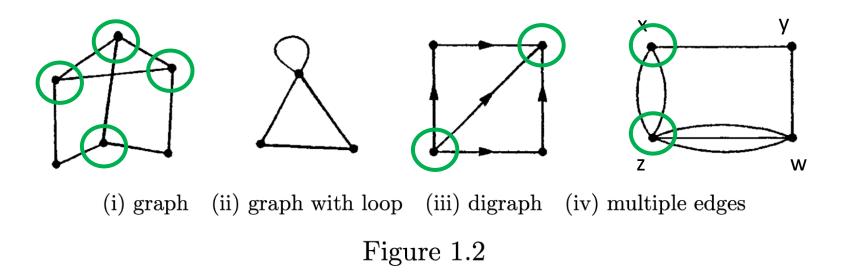


• A graph is finite when both E(G) and V(G) are finite sets

graph with loop

Handshaking Theorem (Euler 1736)

• Theorem A finite graph G has an even number of vertices with odd degree



Proof

- Theorem A finite graph G has an even number of vertices with odd degree.
- Proof The degree of x is the number of times it appears in the right column. Thus

$$\sum_{x \in V(G)} \deg(x) = 2|E(G)|$$

edge	ends
a	x, z
b	y,w
c	x, z
d	z,w
e	z,w
$\int f$	x,y
g	z, w

Figure 1.1

Degree

- Minimal degree of $G: \delta(G) = \min\{d(v): v \in V\}$
- Maximal degree of $G: \Delta(G) = \max\{d(v): v \in V\}$

• Average degree of
$$G: d(G) = \frac{1}{|V|} \sum_{v \in V} d(v) = \frac{2|E|}{|V|}$$

- All measure the `density' of a graph
- $d(G) \ge \delta(G)$

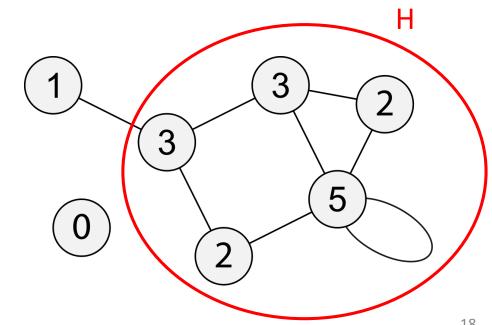
Degree (global to local)

• Proposition (1.2.2, D) Every graph G with at least one edge has a subgraph *H* with . 1

$$\delta(H) > \frac{1}{2}d(H) \ge \frac{1}{2}d(G)$$

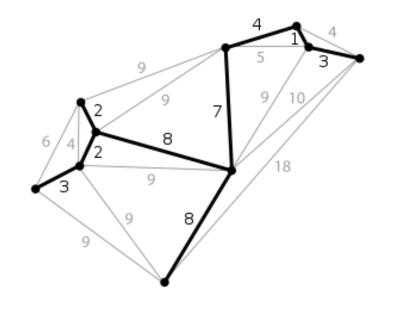
• Example:
$$|G| = 7$$
, $d(G) = \frac{16}{7}$

•
$$\delta(H) = 2, d(H) = \frac{14}{5}$$



Minimal degree guarantees long paths and cycles

• Proposition (1.3.1, D) Every graph G contains a path of length $\delta(G)$ and a cycle of length at least $\delta(G) + 1$, provided $\delta(G) \ge 2$.

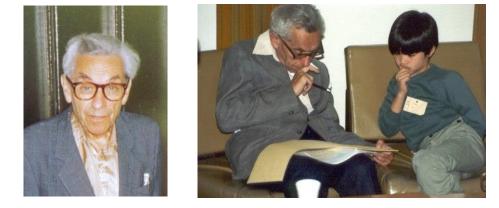


Distance and diameter

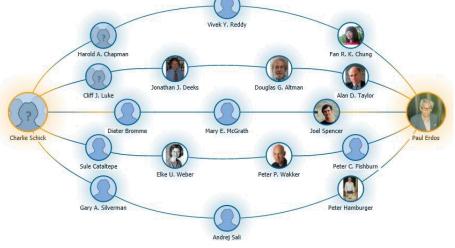
- The distance d_G(x, y) in G of two vertices x, y is the length of a shortest x~y path
 - if no such path exists, we set $d(x, y) \coloneqq \infty$
- The greatest distance between any two vertices in *G* is the diameter of *G*

$$\operatorname{diam}(G) = \max_{x,y \in V} d(x,y)$$

Example -- Erdős number

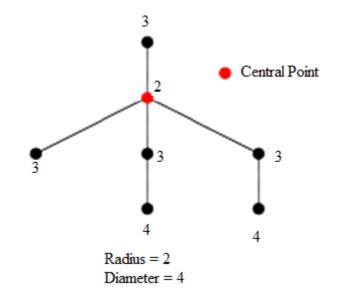


- A well-known graph
 - vertices: mathematicians of the world
 - Two vertices are adjacent if and only if they have published a joint paper
 - The distance in this graph from some mathematician to the vertex Paul Erdős is known as his or her Erdős number



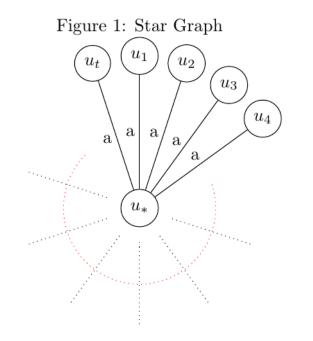
Radius and diameter

- A vertex is central in G if its greatest distance from other vertex is smallest, such greatest distance is the radius of G rad(G) := $\min_{x \in V} \max_{y \in V} d(x, y)$
- Proposition (1.4, H; Ex1.6, D) $rad(G) \le diam(G) \le 2 rad(G)$



Radius and maximum degree control graph size

• Proposition (1.3.3, D) A graph G with radius at most r and maximum degree at most $\Delta \ge 3$ has fewer than $\frac{\Delta}{\Delta - 2} (\Delta - 1)^r$.



Lecture 2: Girth, Connectivity and Bipartite Graphs

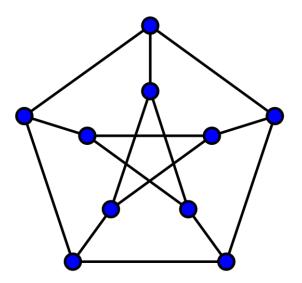
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- The minimum length of a cycle in a graph G is the girth g(G) of G
- Example: The Peterson graph is the unique 5-cage
 - cubic graph (every vertex has degree 3)
 - girth = 5
 - smallest graph satisfies the above properties



Girth (cont.)

- A tree has girth ∞
- Note that a tree can be colored with two different colors
- → A graph with large girth has small chromatic number?
- Unfortunately NO!
- Theorem (Erdős, 1959) For all k, l, there exists a graph G with g(G) > l and $\chi(G) > k$

Girth and diameter

- Proposition (1.3.2, D) Every graph G containing a cycle satisfies $g(G) \le 2 \operatorname{diam}(G) + 1$
- When the equality holds?

Girth and minimal degree lower bounds graph size

•
$$n_0(\delta, g) \coloneqq \begin{cases} 1 + \delta \sum_{i=0}^{r-1} (\delta - 1)^i, & \text{if } g = 2r + 1 \text{ is odd} \\ 2 \sum_{i=0}^{r-1} (\delta - 1)^i, & \text{if } g = 2r \text{ is even} \end{cases}$$

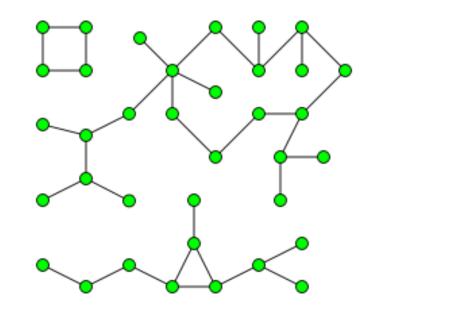
- Exercise (Ex7, ch1, D) Let G be a graph. If $\delta(G) \ge \delta \ge 2$ and $g(G) \ge g$, then $|G| \ge n_0(\delta, g)$
- Corollary (1.3.5, D) If $\delta(G) \ge 3$, then $g(G) < 2 \log_2 |G|$

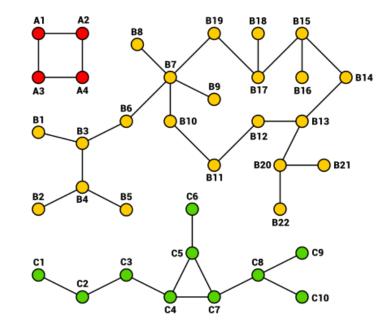
Triangle-free upper bounds # of edges

- Theorem (1.3.23, W, Mantel 1907) The maximum number of edges in an *n*-vertex triangle-free simple graph is $\lfloor n^2/4 \rfloor$
- The bound is best possible
- There is a triangle-free graph with $\lfloor n^2/4 \rfloor$ edges: $K_{\lfloor n/2 \rfloor, \lfloor n/2 \rfloor}$
- Extremal problems

Connected, connected component

- A graph G is connected if G ≠ Ø and any two of its vertices are linked by a path
- A maximal connected subgraph of G is a (connected) component





Quiz

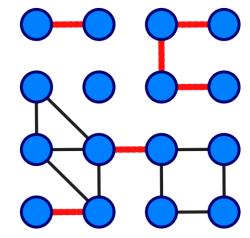
- Problem (1B, L) Suppose G is a graph on 10 vertices that is not connected. Prove that G has at most 36 edges. Can equality occur?
- More general (Ex9, S1.1.2, H) Let G be a graph of order n that is not connected. What is the maximum size of G?

Connected vs. minimal degree

- Proposition (1.3.15, W) If $\delta(G) \ge \frac{n-1}{2}$, then G is connected
- (Ex16, S1.1.2, H; 1.3.16, W) If $\delta(G) \ge \frac{n-2}{2}$, then G need not be connected
- Extremal problems
- "best possible" "sharp"

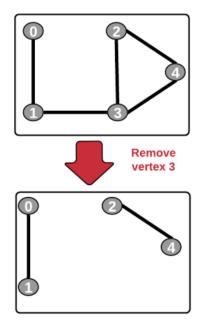
Add/delete an edge

- Components are pairwise disjoint; no two share a vertex
- Adding an edge decreases the number of components by 0 or 1
 - \Rightarrow deleting an edge increases the number of components by 0 or 1
- Proposition (1.2.11, W)
 Every graph with n vertices and k edges has at least n k components
- An edge e is called a bridge if the graph G e has more components
- Proposition (1.2.14, W) An edge e is a bridge $\Leftrightarrow e$ lies on no cycle of G
 - Or equivalently, an edge e is not a bridge $\Leftrightarrow e$ lies on a cycle of G



Cut vertex and connectivity

- A node v is a cut vertex if the graph G v has more components
- A proper subset S of vertices is a vertex cut set if the graph G S is disconnected, or trivial (a graph of order 0 or 1)
- The connectivity, κ(G), is the minimum size of a cut set of G
 - The graph is k-connected for any $k \leq \kappa(G)$



Connectivity properties

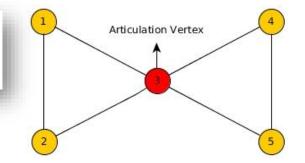
- $\kappa(K^n) = n 1$
- If G is disconnected, $\kappa(G) = 0$
 - \Rightarrow A graph is connected $\Leftrightarrow \kappa(G) \ge 1$
- If G is connected, non-complete graph of order n, then $1 \le \kappa(G) \le n-2$

Connectivity properties (cont.)

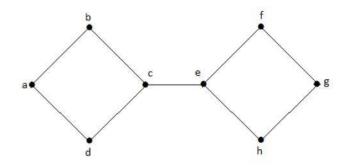
Proposition (1.2.14, W)

An edge e is a bridge $\Leftrightarrow e$ lies on no cycle of G

- Or equivalently, an edge e is not a bridge $\Leftrightarrow e$ lies on a cycle of G
- $\kappa(G) \ge 2 \Leftrightarrow G$ is connected and has no cut vertices

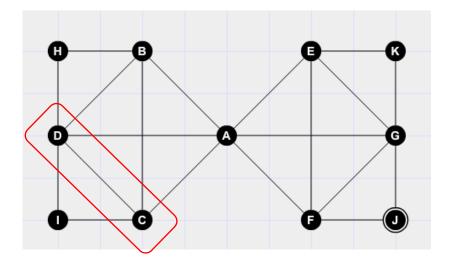


- A vertex lies on a cycle ⇒ it is not a cut vertex
 - \Rightarrow (Ex13, S1.1.2, H) Every vertex of a connected graph G lies on at least one cycle $\Rightarrow \kappa(G) \ge 2$
 - (Ex14, S1.1.2, H) $\kappa(G) \ge 2$ implies G has at least one cycle
- (Ex12, S1.1.2, H) G has a cut vertex vs. G has a bridge



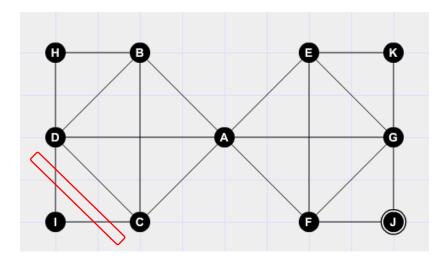
Connectivity and minimal degree

- (Ex15, S1.1.2, H)
- $\kappa(G) \leq \delta(G)$
- If $\delta(G) \ge n 2$, then $\kappa(G) = \delta(G)$



Edge-connectivity

- A proper subset F ⊂ E is edge cut set if the graph G − F is disconnected
- The edge-connectivity $\lambda(G)$ is the minimal size of edge cut set
- $\lambda(G) = 0$ if G is disconnected
- Proposition (1.4.2, D) If G is non-trivial, then $\kappa(G) \leq \lambda(G) \leq \delta(G)$

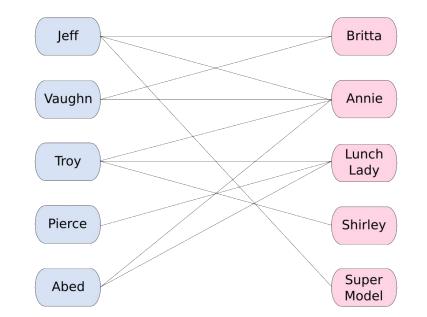


Large average (minimal) degree implies local large connectivity

• Theorem (1.4.3, D, Mader 1972) Every graph G with $d(G) \ge 4k$ has a (k + 1)-connected subgraph H such that d(H) > d(G) - 2k.

Bipartite graphs

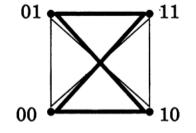
Theorem (1.2.18, W, Kőnig 1936)
 A graph is bipartite ⇔ it contains no odd cycle



Proposition (1.2.15, W) Every closed odd walk contains an odd cycle

Complete graph is a union of bipartite graphs

- The union of graphs G_1, \ldots, G_k , written $G_1 \cup \cdots \cup G_k$, is the graph with vertex set $\bigcup_{i=1}^k V(G_i)$ and edge set $\bigcup_{i=1}^k E(G_i)$
- Consider an air traffic system with k airlines
 - Each pair of cities has direct service from at least one airline
 - No airline can schedule a cycle through an odd number of cities
 - Then, what is the maximum number of cities in the system?



• Theorem (1.2.23, W) The complete graph K_n can be expressed as the union of k bipartite graphs $\Leftrightarrow n \leq 2^k$

Bipartite subgraph is large

• Theorem (1.3.19, W) Every loopless graph G has a bipartite subgraph with at least |E|/2 edges

Lecture 3: Trees

Shuai Li

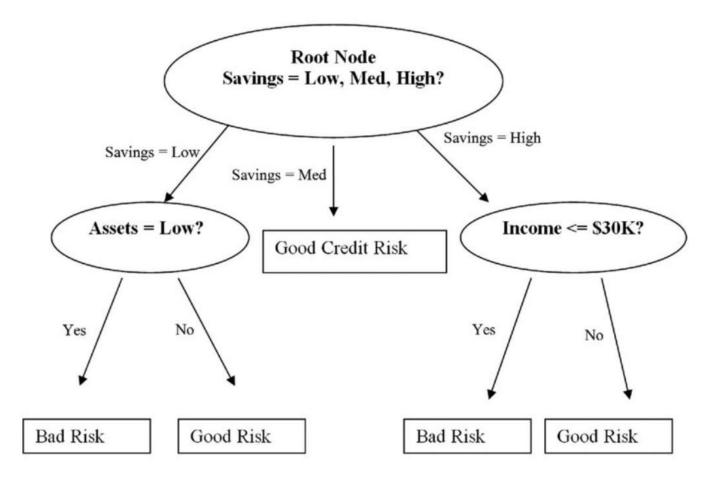
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Trees

• A tree is a connected graph T with no cycles



Properties

Theorem (1.2.18, W, Kőnig 1936)

- Recall that A graph is bipartite \Leftrightarrow it contains no odd cycle
- \Rightarrow (Ex 3, S1.3.1, H) A tree of order $n \ge 2$ is a bipartite graph

Proposition (1.2.14, W)

An edge *e* is a bridge \Leftrightarrow *e* lies on no cycle of *G*

- Recall that • Or equivalently, an edge e is not a bridge \Leftrightarrow e lies on a cycle of G
- \Rightarrow Every edge in a tree is a bridge
- T is a tree \Leftrightarrow T is minimally connected, i.e. T is connected but T eis disconnected for every edge $e \in T$

Equivalent definitions (Theorem 1.5.1, D)

- *T* is a tree of order *n*
 - \Leftrightarrow Any two vertices of T are linked by a unique path in T
 - \Leftrightarrow *T* is minimally connected
 - i.e. T is connected but T e is disconnected for every edge $e \in T$
 - \Leftrightarrow *T* is maximally acyclic
 - i.e. *T* contains no cycle but T + xy does for any non-adjacent vertices $x, y \in T$
 - \Leftrightarrow (Theorem 1.10, 1.12, H) *T* is connected with n 1 edges
 - \Leftrightarrow (Theorem 1.13, H) *T* is acyclic with n 1 edges

Leaves of tree

- A vertex of degree 1 in a tree is called a leaf
- Theorem (1.14, H; Ex9, S1.3.2, H) Let T be a tree of order $n \ge 2$. Then T has at least two leaves
- (Ex3, S1.3.2, H) Let T be a tree with max degree Δ . Then T has at least Δ leaves
- (Ex10, S1.3.2, H) Let T be a tree of order $n \ge 2$. Then the number of leaves is

$$2 + \sum_{v:d(v) \ge 3} (d(v) - 2)$$

- (Ex8, S1.3.2, H) Every nonleaf in a tree is a cut vertex
- Every leaf node is not a cut vertex

The center of a tree is a vertex or 'an edge'

• Theorem (1.15, H) In any tree, the center is either a single vertex or a pair of adjacent vertices

Any tree can be embedded in a 'dense' graph

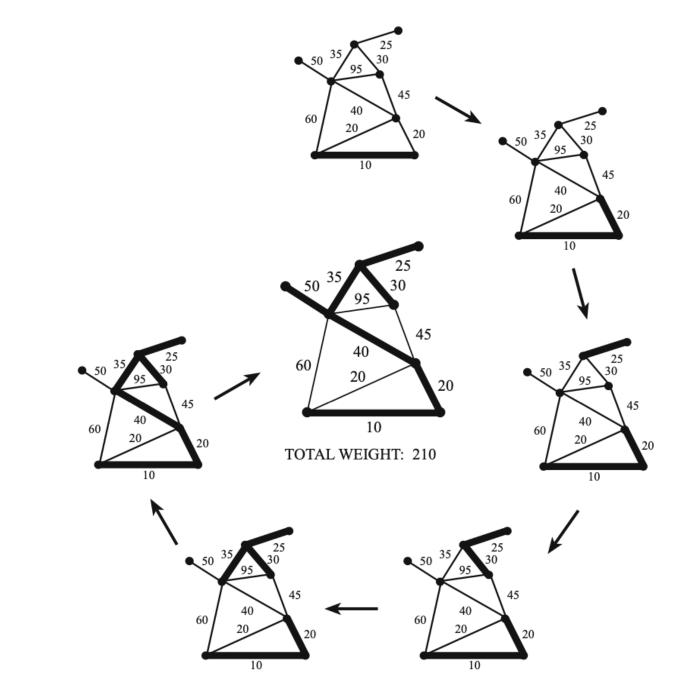
• Theorem (1.16, H) Let T be a tree of order k + 1 with k edges. Let G be a graph with $\delta(G) \ge k$. Then G contains T as a subgraph

Spanning tree

- Given a graph G and a subgraph T, T is a spanning tree of G if T is a tree that contains every vertex of G
- Example: A telecommunications company tries to lay cable in a new neighbourhood
- Proposition (2.1.5c, W) Every connected graph contains a spanning tree

Minimal spanning tree - Kruskal's Algorithm

- Given: A connected, weighted graph G
- 1. Find an edge of minimum weight and mark it.
- 2. Among all of the unmarked edges that do not form a cycle with any of the marked edges, choose an edge of minimum weight and mark it
- 3. If the set of marked edges forms a spanning tree of G, then stop. If not, repeat step 2



Example

FIGURE 1.43. The stages of Kruskal's algorithm.

Theoretical guarantee of Kruskal's algorithm

• Theorem (1.17, H) Kruskal's algorithm produces a spanning tree of minimum total weight

Cayley's tree formula

- Theorem (1.18, H; 2.2.3, W). There are n^{n-2} distinct labeled trees of order n

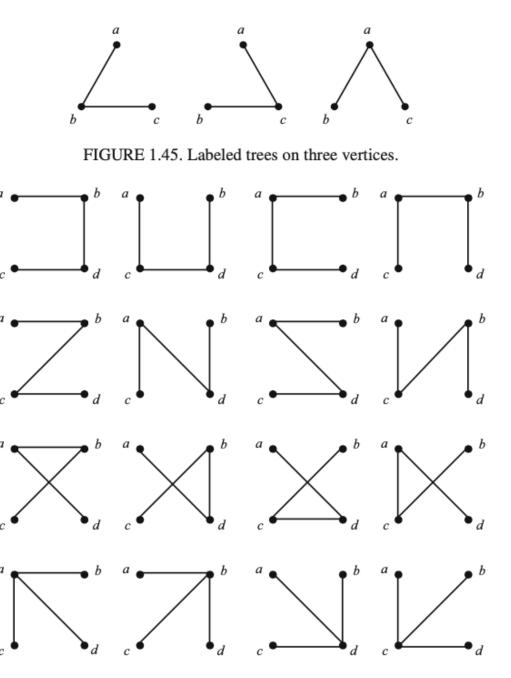
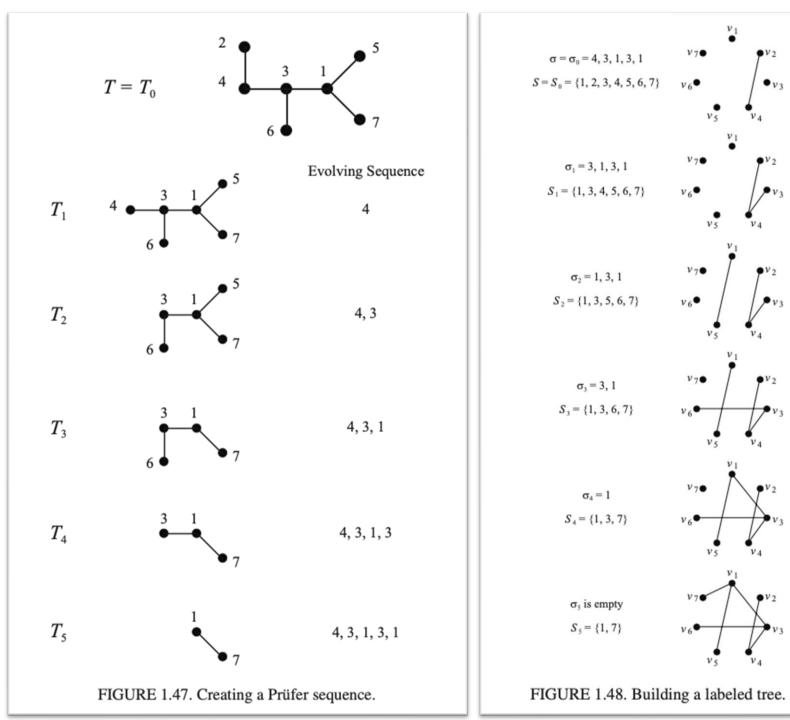


FIGURE 1.46. Labeled trees on four vertices.

Example



55

•v2

•v3

 \mathbf{P}_{V_3}

•v2

Pv3

VA

VA

•V2

•V2

 v_4

v 5

v 5

VS

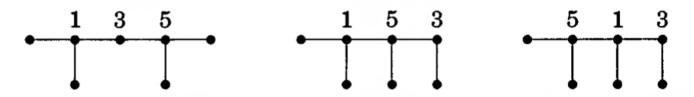
VS

VS

VS

of trees with fixed degree sequence

- Corollary (2.2.4, W) Given positive integers d_1, \ldots, d_n summing to 2n-2, there are exactly $\frac{(n-2)!}{\prod(d_i-1)!}$ trees with vertex set [n] such that vertex i has degree d_i for each i
- Example (2.2.5, W) Consider trees with vertices [7] that have degrees (3,1,2,1,3,1,1)



Matrix tree theorem - cofactor

• For an *n* × *n* matrix *A*, the *i*, *j* cofactor of *A* is defined to be

 $(-1)^{i+j} \det(M_{ij})$ where M_{ij} represents the $(n-1) \times (n-1)$ matrix formed by deleting row iand column j from A $3 \times 3 \text{ generic matrix [edit]}$ Consider a 3×3 matrix $\mathbf{A} = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix}.$ Its cofactor matrix is $\mathbf{C} = \begin{pmatrix} +\begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} - \begin{vmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{vmatrix} + \begin{vmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{vmatrix}$ $+\begin{vmatrix} a_{12} & a_{13} \\ a_{32} & a_{33} \end{vmatrix} + \begin{vmatrix} a_{11} & a_{13} \\ a_{31} & a_{33} \end{vmatrix} - \begin{vmatrix} a_{11} & a_{12} \\ a_{31} & a_{32} \end{vmatrix},$ $+\begin{vmatrix} a_{12} & a_{13} \\ a_{22} & a_{23} \end{vmatrix} + \begin{vmatrix} a_{11} & a_{13} \\ a_{31} & a_{33} \end{vmatrix} + \begin{vmatrix} a_{11} & a_{12} \\ a_{31} & a_{32} \end{vmatrix},$

Matrix tree theorem

- Theorem (1.19, H; 2.2.12, W; Kirchhoff) If G is a connected labeled graph with adjacency matrix A and degree matrix D, then the number of unique spanning trees of G is equal to the value of any cofactor of the matrix D A
- If the row sums and column sums of a matrix are all 0, then the cofactors all have the same value
- Exercise Read the proof
- Exercise (Ex7, S1.3.4, H) Use the matrix tree theorem to prove Cayley's theorem

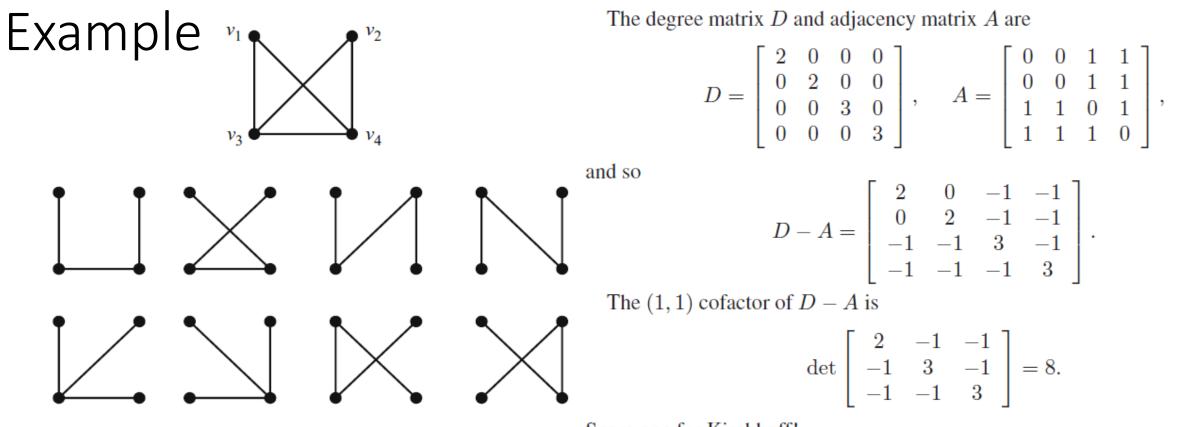


FIGURE 1.49. A labeled graph and its spanning trees.

Score one for Kirchhoff!

• Exercise (Ex6, S1.3.4, H) Let e be an edge of K_n . Use Cayley's Theorem to prove that $K_n - e$ has $(n - 2)n^{n-3}$ spanning trees

Wiener index

• In a communication network, large diameter may be acceptable if most pairs can communicate via short paths. This leads us to study the average distance instead of the maximum

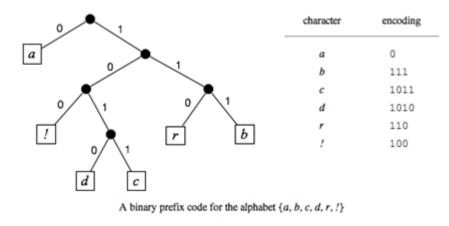
• Wiener index
$$D(G) = \sum_{u,v \in V(G)} d_G(u,v)$$

- Theorem (2.1.14, W) Among trees with n vertices, the Wiener index D(T) is minimized by stars and maximized by paths, both uniquely
- Over all connected *n*-vertex graphs, D(G) is minimized by K_n and maximized (2.1.16, W) by paths
 - (Lemma 2.1.15, W) If H is a subgraph of G, then $d_G(u, v) \le d_H(u, v)$

Prefix coding

- A binary tree is a rooted plane tree where each vertex has at most two children
- Given large computer files and limited storage, we want to encode characters as binary lists to minimize (expected) total length
- Prefix-free coding: no code word is an initial portion of another

• Example: 11001111011

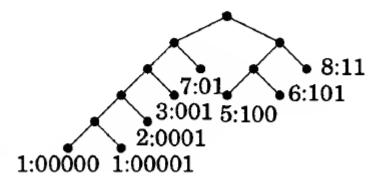


Huffman's Algorithm (2.3.13, W)

- Input: Weights (frequencies or probabilities) p_1, \ldots, p_n
- Output: Prefix-free code (equivalently, a binary tree)
- Idea: Infrequent items should have longer codes; put infrequent items deeper by combining them into parent nodes.
- Recursion: replace the two least likely items with probabilities p,p^\prime with a single item of weight $p+p^\prime$

Example (2.3.14, W)

а	5	100
b	1	00000
С	1	00001
d	7	01
е	8	11
f	2	0001
g	3	001
h	6	101



The average length is
$$\frac{5 \times 3 + 5 + 5 + 7 \times 2 + \cdots}{33} = \frac{30}{11} < 3$$

Huffman coding is optimal

• Theorem (2.3.15, W) Given a probability distribution $\{p_i\}$ on n items, Huffman's Algorithm produces the prefix-free code with minimum expected length

Huffman coding and entropy

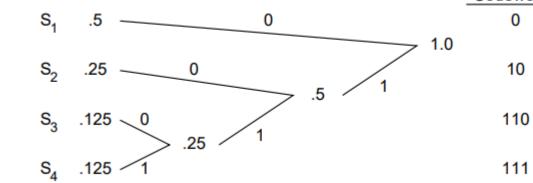
• The entropy of a discrete probability distribution $\{p_i\}$ is that

$$H(p) = -\sum_{i} p_i \log_2 p_i$$

- Exercise (Ex2.3.31, W) $H(p) \leq$ average length of Huffman coding \leq H(p) + 1
- Exercise (Ex2.3.30, W) When each p_i is a power of $\frac{1}{2}$, average length of Huffman coding is H(p)Codewords

0

10



average length =
$$(1)\left(\frac{1}{2}\right) + (2)\left(\frac{1}{4}\right) + (3)\left(\frac{1}{8}\right) + (3)\left(\frac{1}{8}\right)$$

= 1.75 bits/symbol

$$H = \frac{1}{2}\log_2 2 + \frac{1}{4}\log_2 4 + \frac{1}{8}\log_2 8 + \frac{1}{8}\log_2 8$$

= $\frac{1}{2} + \frac{1}{2} + \frac{3}{8} + \frac{3}{8}$
= 1.75 65

Lecture 4: Circuits

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https://shuaili8.github.io/Teaching/CS445/index.html

Eulerian circuit

- A closed walk through a graph using every edge once is called an Eulerian circuit
- A graph that has such a walk is called an Eulerian graph
- Theorem (1.2.26, W) A graph G is Eulerian ⇔ it has at most one nontrivial component and its vertices all have even degree
- (possibly with multiple edges)
- Proof "⇒" That G must be connected is obvious.
 Since the path enters a vertex through some edge and leaves by another edge, it is clear that all degrees must be even

Key lemma

• Lemma (1.2.25, W) If every vertex of a graph G has degree at least 2, then G contains a cycle.

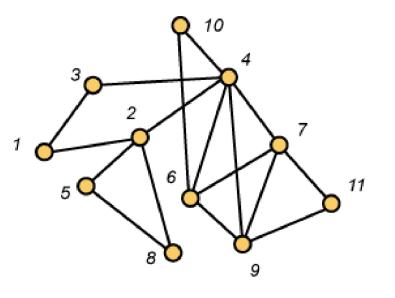
Proposition (1.3.1, D) Every graph G contains a path of length $\delta(G)$ and a cycle of length at least $\delta(G) + 1$, provided $\delta(G) \ge 2$.

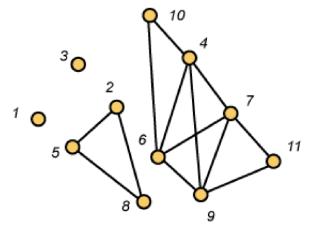
Hierholzer's Algorithm for Euler Circuits

- 1. Choose a root vertex r and start with the trivial partial circuit (r)
- 2. Given a partial circuit $(x_0, e_1, x_1, \dots, x_{t-1}, e_t, x_t = x_0)$ that traverses not all edges of G, remove these edges from G
- 3. Let i be the least integer for which x_i is incident with one of the remaining edges
- 4. Form a greedy partial circuit among the remaining edges of the form $(x_i = y_0, e'_1, y_1, \dots, y_{s-1}, e'_s, y_s = x_i)$
- 5. Expand the original circuit by setting $(x_0, e_1, ..., e_i, x_i = y_0, e'_1, y_1, ..., y_{s-1}, e'_s, y_s = x_i, e_{i+1}, ..., e_t, x_t = x_0)$
- 6. Repeat step 2-5

Example

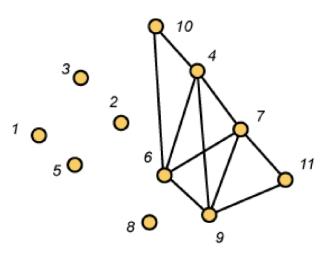
- 1. Start with the trivial circuit (1)
- 2. Greedy algorithm yields the partial circuit (1,2,4,3,1)
- 3. Remove these edges
- 4. The first vertex incident with remaining edges is 2
- 5. Greedy algorithms yields (2,5,8,2)
- 6. Expanding (1,2,5,8,2,4,3,1)
- 7. Remove these edges

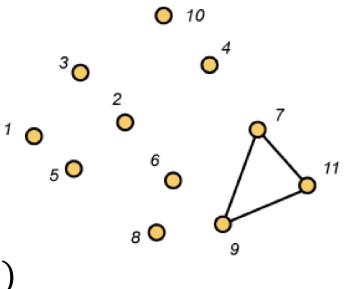




Example (cont.)

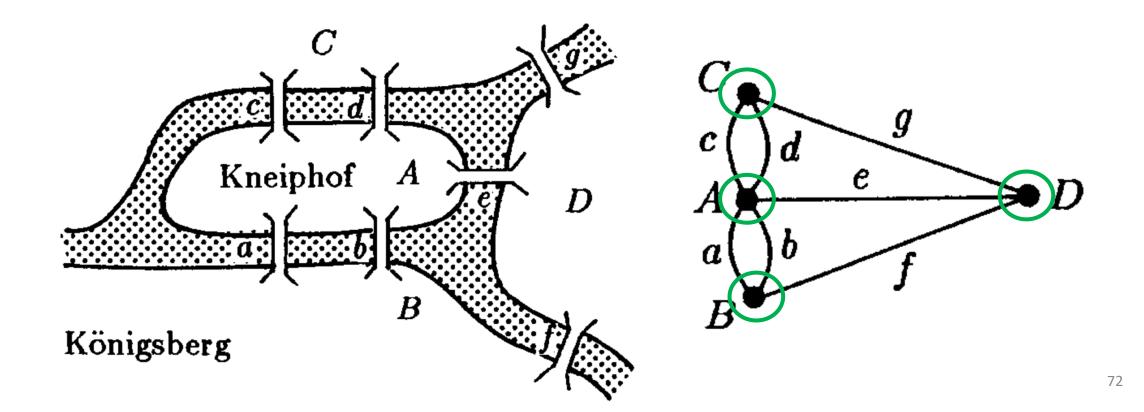
- 6. Expanding (1,2,5,8,2,4,3,1)
- 7. Remove these edges
- 8. First vertex incident with remaining edges is 4
- 9. Greedy algorithm yields (4,6,7,4,9,6,10,4)
 10. Expanding (1,2,5,8,2,4,6,7,4,9,6,10,4,3,1)
- 11. Remove these edges
- 12. First vertex incident with remaining edges is 7
- 13. Greedy algorithm yields (7,9,11,7)
- 14. Expanding (1,2,5,8,2,4,6,7,9,11,7,4,9,6,10,4,3,1)





Eulerian circuit

 Theorem (1.2.26, W) A graph G is Eulerian ⇔ it has at most one nontrivial component and its vertices all have even degree



Other properties

- Proposition (1.2.27, W) Every even graph decomposes into cycles
- The necessary and sufficient condition for a directed Eulerian circuit is that the graph is connected and that each vertex has the same 'indegree' as 'out-degree'

TONCAS

- TONCAS: The obvious necessary condition is also sufficient
- Theorem (1.2.26, W) A graph G is Eulerian ⇔ it has at most one nontrivial component and its vertices all have even degree
- Proposition (1.3.28, W) The nonnegative integers d_1, \ldots, d_n are the vertex degrees of some graph $\Leftrightarrow \sum_{i=1}^n d_i$ is even
- (Possibly with loops)
- Otherwise (2,0,0) is not realizable
- **1.3.63.** (!) Let d_1, \ldots, d_n be integers such that $d_1 \ge \cdots \ge d_n \ge 0$. Prove that there is a loopless graph (multiple edges allowed) with degree sequence d_1, \ldots, d_n if and only if $\sum d_i$ is even and $d_1 \le d_2 + \cdots + d_n$. (Hakimi [1962])

Hamiltonian path/circuits

- A path P is Hamiltonian if V(P) = V(G)
 - Any graph contains a Hamiltonian path is called traceable
- A cycle C is called Hamiltonian if it spans all vertices of G
 - A graph is called Hamiltonian if it contains a Hamiltonian circuit
- In the mid-19th century, Sir William Rowan Hamilton tried to popularize the exercise of finding such a closed path in the graph of the dodecahedron (正十二面体)

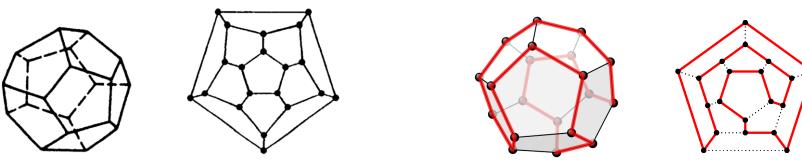
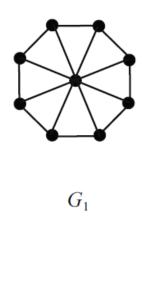


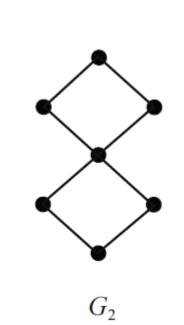
Figure 1.9

Degree parity is not a criterion

Theorem (1.2.26, W) A graph G is Eulerian \Leftrightarrow it has at most one nontrivial component and its vertices all have even degree

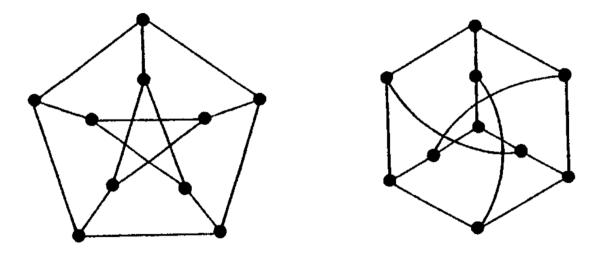
- Hamiltonian graphs
 - all even degrees C₁₀
 - all odd degrees K₁₀
 - a mixture G_1
- non-Hamiltonian graphs
 - all even G_2
 - all odd *K*_{5,7}
 - mixed P_9





Example

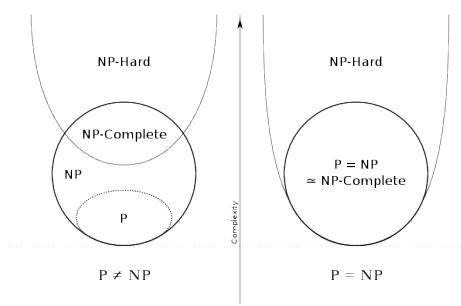
• The Petersen graph has a Hamiltonian path but no Hamiltonian cycle



• Determining whether such paths and cycles exist in graphs is the Hamiltonian path problem, which is NP-complete

P, NP, NPC, NP-hard

- P The general class of questions for which some algorithm can provide an answer in polynomial time
- NP (nondeterministic polynomial time) The class of questions for which an answer can be *verified* in polynomial time
- NP-Complete
 - 1. c is in NP
 - 2. Every problem in NP is reducible to c in polynomial time
- NP-hard
 - c is in NP
 - Every problem in NP is reducible to c in polynomial time



Large minimal degree implies Hamiltonian

• Theorem (1.22, H, Dirac) Let G be a graph of order $n \ge 3$. If $\delta(G) \ge n/2$, then G is Hamiltonian

Proposition (1.3.15, W) If $\delta(G) \ge \frac{n-1}{2}$, then *G* is connected (Ex16, S1.1.2, H) (1.3.16, W) If $\delta(G) \ge \frac{n-2}{2}$, then *G* need not be connected

- The bound is tight (Ex12b, S1.4.3, H) $G = K_{r,r+1}$ is not Hamiltonian Exercise The condition when $K_{r,s}$ is Hamiltonian
- The condition is not necessary
 - C_n is Hamiltonian but with small minimum (and even maximum) degree

Generalized version

• Exercise (Theorem 1.23, H, Ore; Ex3, S1.4.3, H) Let G be a graph of order $n \ge 3$. If $deg(x) + deg(y) \ge n$ for all pairs of nonadjacent vertices x, y, then G is Hamiltonian

Theorem (1.22, H, Dirac) Let G be a graph of order $n \ge 3$. If $\delta(G) \ge n/2$, then G is Hamiltonian

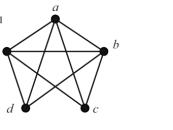
Independence number & Hamiltonian

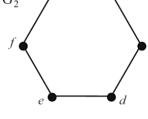
- A set of vertices in a graph is called independent if they are pairwise nonadjacent
- The independence number of a graph G, denoted as α(G), is the largest size of an independent set

• Example:
$$\alpha(G_1) = 2, \alpha(G_2) = 3$$

• Theorem (1.24, H) Let G be a connected graph of order $n \ge 3$. If $\kappa(G) \ge \alpha(G)$, then G is Hamiltonian

(Ex14, S1.1.2, H) $\kappa(G) \ge 2$ implies G has at least one cycle





Independence number & Hamiltonian 2

Theorem (1.24, H) Let G be a connected graph of order $n \ge 3$. If $\kappa(G) \ge \alpha(G)$, then G is Hamiltonian

• The result is tight: $\kappa(G) \ge \alpha(G) - 1$ is not enough

•
$$K_{r,r+1}: \kappa = r, \alpha = r+1$$

• Exercise (Ex4, S1.4.3, H) Peterson graph: $\kappa = 3$, $\alpha = 4$

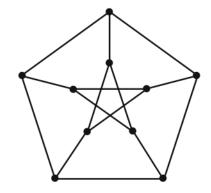
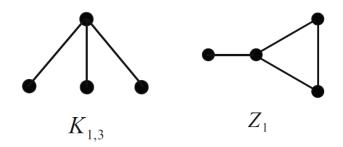


FIGURE 1.63. The Petersen Graph.

Pattern-free & Hamiltonian



- *G* is *H*-free if *G* doesn't contain a copy of *H* as induced subgraph
- Theorem (1.25, H) If G is 2-connected and $\{K_{1,3}, Z_1\}$ -free, then G is Hamiltonian

(Ex14, S1.1.2, H) $\kappa(G) \ge 2$ implies G has at least one cycle

- The condition 2-connectivity is necessary
- (Ex2, S1.4.3, H) If G is Hamiltonian, then G is 2-connected

Lecture 5: Matchings

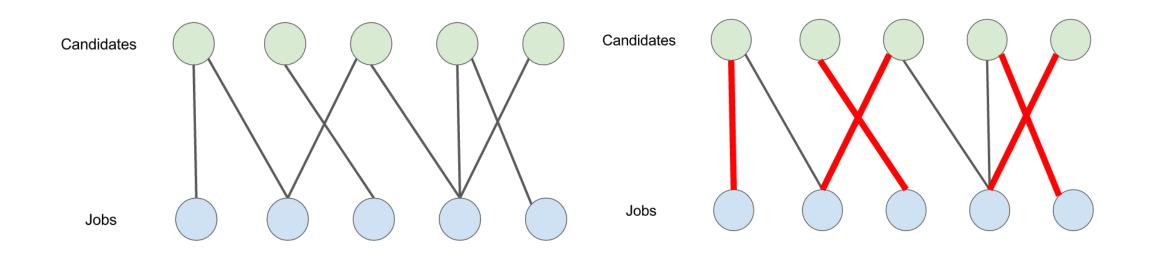
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https://shuaili8.github.io/Teaching/CS445/index.html

Motivating example



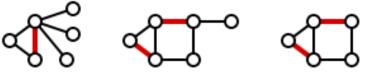
Definitions

- A matching is a set of independent edges, in which no pair of edges shares a vertex
- The vertices incident to the edges of a matching *M* are *M*-saturated (饱和的); the others are *M*-unsaturated
- A perfect matching in a graph is a matching that saturates every vertex
- Example (3.1.2, W) The number of perfect matchings in $K_{n,n}$ is n!
- Example (3.1.3, W) The number of perfect matchings in K_{2n} is $f_n = (2n-1)(2n-3) \cdots 1 = (2n-1)!!$

Maximal/maximum matchings 极大/最大

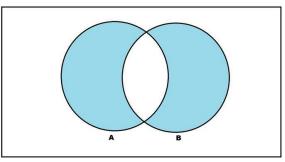
- A maximal matching in a graph is a matching that cannot be enlarged by adding an edge
- A maximum matching is a matching of maximum size among all matchings in the graph
- Example: P_3 , P_5



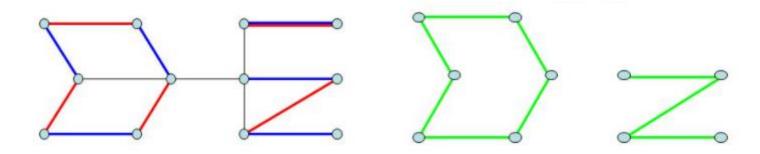


• Every maximum matching is maximal, but not every maximal matching is a maximum matching

Symmetric difference of matchings



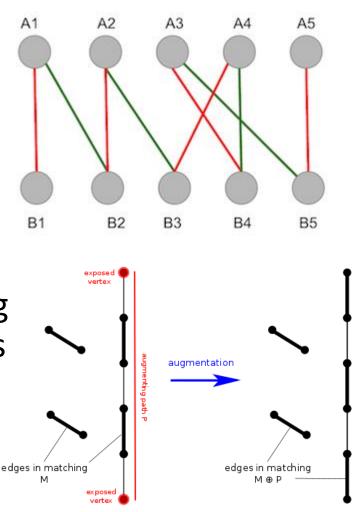
- The symmetric difference of M, M' is $M\Delta M' = (M M') \cup (M' M)$
- Lemma (3.1.9, W) Every component of the symmetric difference of two matchings is a path or an even cycle



Maximum matching and augmenting path

- Given a matching *M*, an *M*-alternating path is a path that alternates between edges in *M* and edges not in *M*
- An *M*-alternating path whose endpoints are *M*-unsaturated is an *M*-augmenting path
- Theorem (3.1.10, W; 1.50, H; Berge 1957) A matching M in a graph G is a maximum matching in G ⇔ G has no M-augmenting path

Lemma (3.1.9, W) Every component of the symmetric difference of two matchings is a path or an even cycle



Hall's theorem (TONCAS)

- Theorem (3.1.11, W; 1.51, H; 2.1.2, D; Hall 1935) Let *G* be a bipartite graph with partition *X*, *Y*.
 - G contains a matching of $X \Leftrightarrow |N(S)| \ge |S|$ for all $S \subseteq X$

Theorem (3.1.10, W; 1.50, H; Berge 1957) A matching M in a graph G is a maximum matching in $G \Leftrightarrow G$ has no M-augmenting path

- Exercise. Read the other two proofs in Diestel.
- Corollary (3.1.13, W; 2.1.3, D) Every k-regular (k > 0) bipartite graph has a perfect matching

General regular graph

- Corollary (2.1.5, D) Every regular graph of positive even degree has a 2-factor
 - A k-regular spanning subgraph is called a k-factor
 - A perfect matching is a 1-factor

Theorem (1.2.26, W) A graph G is Eulerian \Leftrightarrow it has at most one nontrivial component and its vertices all have even degree

Corollary (3.1.13, W; 2.1.3, D) Every k-regular (k > 0) bipartite graph has a perfect matching

Application to SDR

• Given some family of sets *X*, a system of distinct representatives for the sets in *X* is a 'representative' collection of distinct elements from the sets of *X*

$$S_1 = \{2, 8\},$$

$$S_2 = \{8\},$$

$$S_3 = \{5, 7\},$$

$$S_4 = \{2, 4, 8\},$$

$$S_5 = \{2, 4\}.$$

The family $X_1 = \{S_1, S_2, S_3, S_4\}$ does have an SDR, namely $\{2, 8, 7, 4\}$. The family $X_2 = \{S_1, S_2, S_4, S_5\}$ does not have an SDR.

Theorem(1.52, H) Let S₁, S₂, ..., S_k be a collection of finite, nonempty sets. This collection has SDR ⇔ for every t ∈ [k], the union of any t of these sets contains at least t elements

Theorem (3.1.11, W; 1.51, H; 2.1.2, D; Hall 1935) Let G be a bipartite graph with partition X, Y. G contains a matching of $X \Leftrightarrow |N(S)| \ge |S|$ for all $S \subseteq X$

König Theorem Augmenting Path Algorithm

Vertex cover

- A set $U \subseteq V$ is a (vertex) cover of E if every edge in G is incident with a vertex in U
- Example:
 - Art museum is a graph with hallways are edges and corners are nodes
 - A security camera at the corner will guard the paintings on the hallways
 - The minimum set to place the cameras?

König-Egeváry Theorem (Min-max theorem)

Theorem (3.1.16, W; 1.53, H; 2.1.1, D; König 1931; Egeváry 1931)
 Let G be a bipartite graph. The maximum size of a matching in G is equal to the minimum size of a vertex cover of its edges

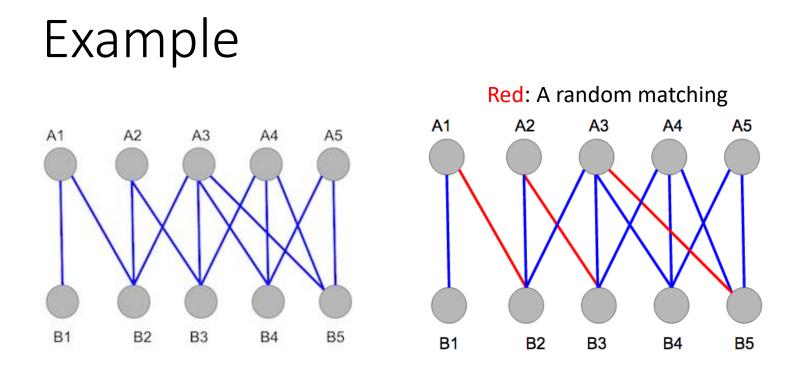
Theorem (3.1.10, W; 1.50, H; Berge 1957) A matching M in a graph G is a maximum matching in $G \Leftrightarrow G$ has no M-augmenting path

Augmenting path algorithm (3.2.1, W)

- Input: G is Bipartite with X, Y, a matching M in G
 U = {M-unsaturated vertices in X }
- Idea: Explore *M*-alternating paths from *U* letting $S \subseteq X$ and $T \subseteq Y$ be the sets of vertices reached
- Initialization: $S = U, T = \emptyset$ and all vertices in S are unmarked
- Iteration:
 - If S has no unmarked vertex, stop and report $T \cup (X S)$ as a minimum cover and M as a maximum matching

X

- Otherwise, select an unmarked $x \in S$ to explore
 - Consider each $y \in N(x)$ such that $xy \notin M$
 - If y is unsaturated, terminate and report an M-augmenting path from U to y
 - Otherwise, $yw \in M$ for some w
 - include *y* in *T* (reached from *x*) and include *w* in *S* (reached from *y*)
 - After exploring all such edges incident to x, mark x and iterate.



Theoretical guarantee for Augmenting path algorithm

• Theorem (3.2.2, W) Repeatedly applying the Augmenting Path Algorithm to a bipartite graph produces a matching and a vertex cover of equal size

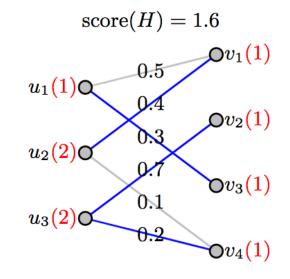
Weighted Bipartite Matching Hungarian Algorithm

Weighted bipartite matching

- The maximum weighted matching problem is to seek a perfect matching *M* to maximize the total weight *w*(*M*)
- Bipartite graph
 - W.I.o.g. Assume the graph is $K_{n,n}$ with $w_{i,j} \ge 0$ for all $i, j \in [n]$
 - Optimization:

$$\max w(M_a) = \sum_{\substack{i,j \\ i,j}} a_{i,j} w_{i,j}$$

s.t. $a_{i,1} + \dots + a_{i,n} \le 1$ for any i
 $a_{1,j} + \dots + a_{n,j} \le 1$ for any j
 $a_{i,j} \in \{0,1\}$



- Integer programming
- General IP problems are NP-Complete

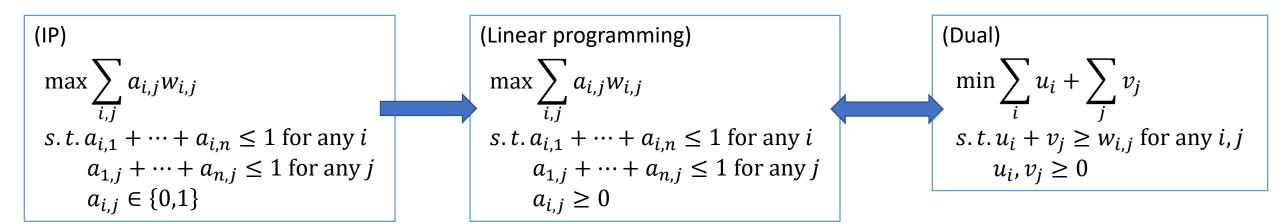
(Weighted) cover

- A (weighted) cover is a choice of labels $u_1, ..., u_n$ and $v_1, ..., v_n$ such that $u_i + v_j \ge w_{i,j}$ for all i, j
 - The cost c(u, v) of a cover (u, v) is $\sum_i u_i + \sum_j v_j$
 - The minimum weighted cover problem is that of finding a cover of minimum cost
- Optimization problem

$$\min c(u, v) = \sum_{i} u_{i} + \sum_{j} v_{j}$$

s.t. $u_{i} + v_{j} \ge w_{i,j}$ for any i, j
 $u_{i}, v_{j} \ge 0$ for any i, j

Duality



- Weak duality theorem
 - For each feasible solution *a* and (*u*, *v*)

$$\sum_{i,j} a_{i,j} w_{i,j} \leq \sum_{i} u_i + \sum_{j} v_j$$

thus max $\sum_{i,j} a_{i,j} w_{i,j} \leq \min \sum_{i} u_i + \sum_{j} v_j$

Duality (cont.)

- Strong duality theorem
 - If one of the two problems has an optimal solution, so does the other one and that the bounds given by the weak duality theorem are tight

$$\max \sum_{i,j} a_{i,j} w_{i,j} = \min \sum_i u_i + \sum_j v_j$$

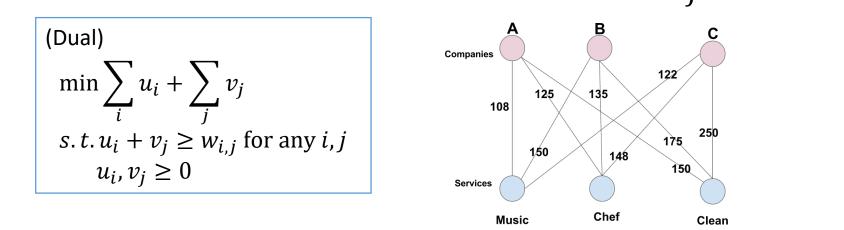
• Lemma (3.2.7, W) For a perfect matching M and cover (u, v) in a weighted bipartite graph G, $c(u, v) \ge w(M)$. $c(u, v) = w(M) \Leftrightarrow M$ consists of edges $x_i y_j$ such that $u_i + v_j = w_{i,j}$ In this case, M and (u, v) are optimal.

Equality subgraph

- The equality subgraph $G_{u,v}$ for a cover (u, v) is the spanning subgraph of $K_{n,n}$ having the edges $x_i y_j$ such that $u_i + v_j = w_{i,j}$
 - So if c(u, v) = w(M) for some perfect matching M, then M is composed of edges in $G_{u,v}$
 - And if $G_{u,v}$ contains a perfect matching M, then (u, v) and M (whose weights are $u_i + v_j$) are both optimal

Hungarian algorithm

- Input: Weighted $K_{n,n} = B(X, Y)$
- Idea: Iteratively adjusting the cover (u, v) until the equality subgraph $G_{u,v}$ has a perfect matching
- Initialization: Let (u, v) be a cover, such as $u_i = \max_i w_{i,j}$, $v_j = 0$



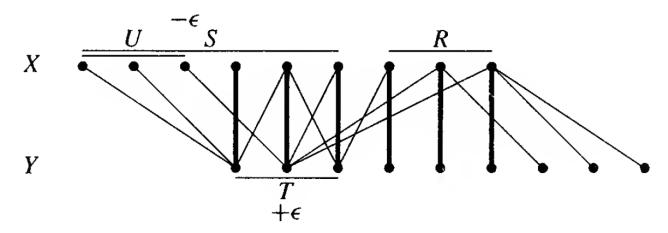
Hungarian algorithm (cont.)

- **Iteration**: Find a maximum matching M in $G_{u,v}$
 - If *M* is a perfect matching, stop and report *M* as a maximum weight matching
 - Otherwise, let Q be a vertex cover of size |M| in $G_{u,v}$

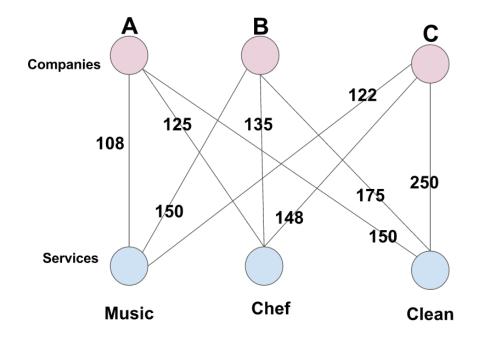
• Let
$$R = X \cap Q$$
, $T = Y \cap Q$
 $\epsilon = \min\{u_i + v_j - w_{i,j} : x_i \in X - R, y_j \in Y - T\}$

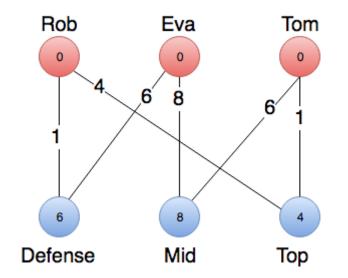
• Decrease u_i by ϵ for $x_i \in X - R$ and increase v_j by ϵ for $y_j \in T$

• Form the new equality subgraph and repeat



Example





Example 2: Excess matrix

5

3

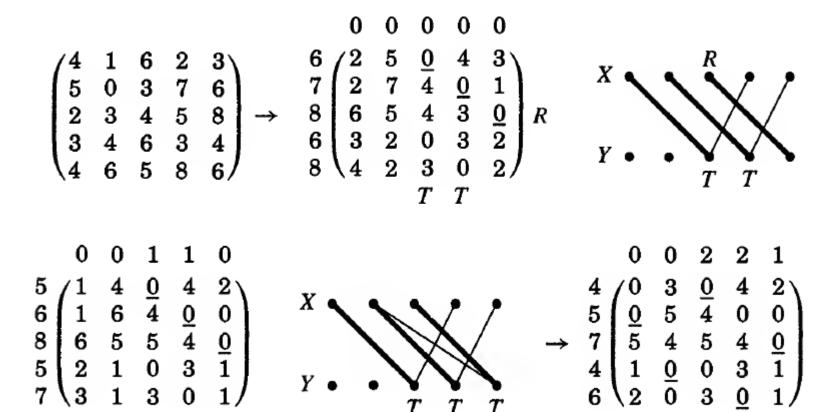
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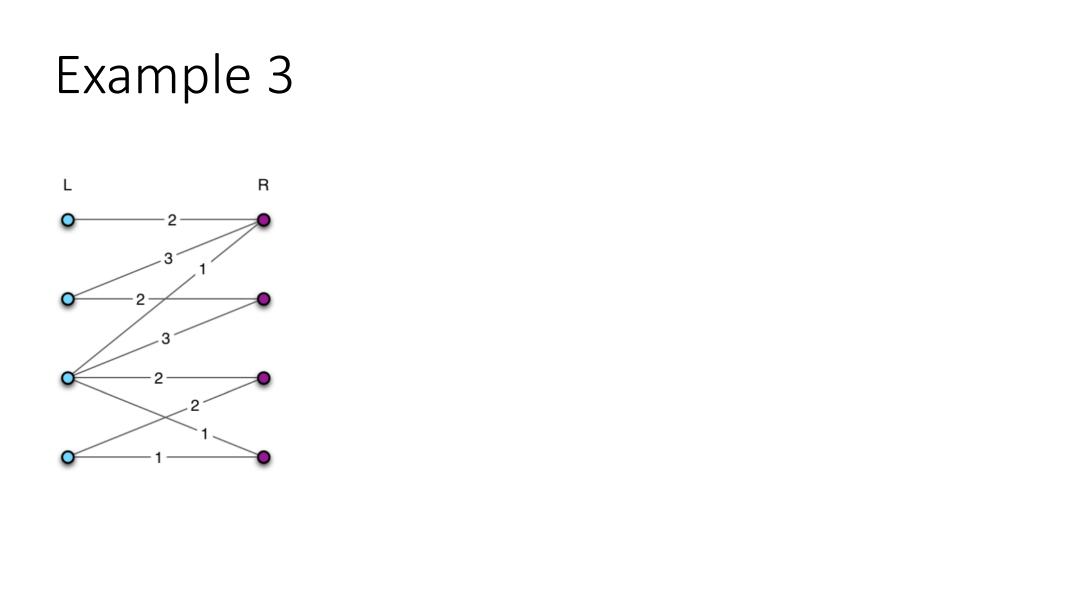
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0

Optimal value is the same But the solution is not unique

Theoretical guarantee for Hungarian algorithm

• Theorem (3.2.11, W) The Hungarian Algorithm finds a maximum weight matching and a minimum cost cover



Back to (unweighted) bipartite graph

- The weights are binary 0,1
- Hungarian algorithm always maintain integer labels in the weighted cover, thus the solution will always be 0,1
- The vertices receiving label 1 must cover the weight on the edges, thus cover all edges
- So the solution is a minimum vertex cover

Stable Matchings

Stable matching

- A family (≤_v)_{v∈V} of linear orderings ≤_v on E(v) is a set of preferences for G
- A matching *M* in *G* is stable if for any edge $e \in E \setminus M$, there exists an edge $f \in M$ such that *e* and *f* have a common vertex *v* with $e <_v f$
 - Unstable: There exists $xy \in E \setminus M$ but $xy', x'y \in M$ with $xy' <_x xy x'y <_y xy$

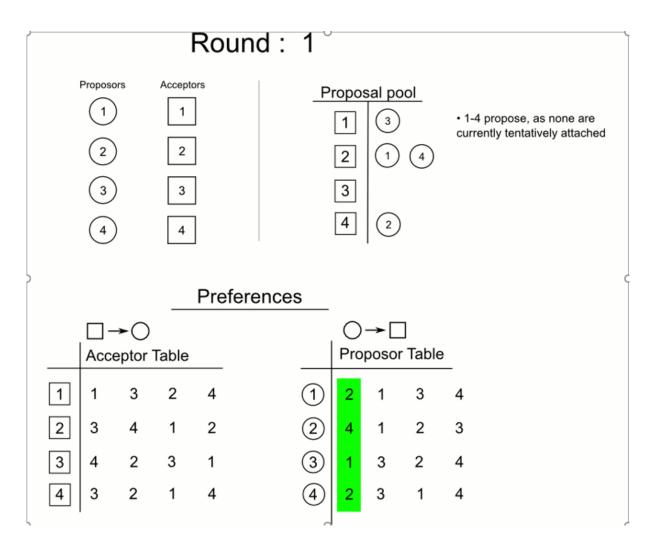
3.2.16. Example. Given men x, y, z, w, women a, b, c, d, and preferences listed below, the matching $\{xa, yb, zd, wc\}$ is a stable matching.

Men $\{x, y, z, w\}$ Women $\{a, b, c, d\}$ x: a > b > c > da: z > x > y > wy: a > c > b > db: y > w > x > zz: c > d > a > bc: w > x > y > zw: c > b > a > dd: x > y > z > w

Gale-Shapley Proposal Algorithm

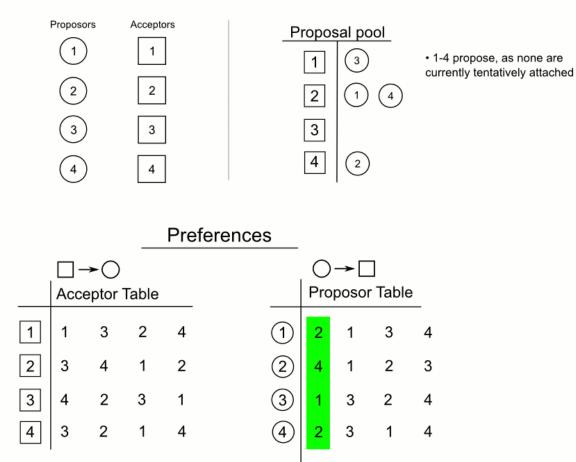
- Input: Preference rankings by each of n men and n women
- Idea: Produce a stable matching using proposals by maintaining information about who has proposed to whom and who has rejected whom
- Iteration: Each man proposes to the highest woman on his preference list who has not previously rejected him
 - If each woman receives exactly one proposal, stop and use the resulting matching
 - Otherwise, every woman receiving more than one proposal rejects all of them except the one that is highest on her preference list
 - Every woman receiving a proposal says "maybe" to the most attractive proposal received

Example





Round : 1



Theoretical guarantee for the Proposal Algorithm

- Theorem (3.2.18, W, Gale-Shapley 1962) The Proposal Algorithm produces a stable matching
- Who proposes matters (jobs/candidates)
- Exercise Among all stable matchings, every man is happiest in the one produced by the male-proposal algorithm and every woman is happiest under the female-proposal algorithm

3.2.16. Example. Given men x, y, z, w, women a, b, c, d, and preferences listed below, the matching $\{xa, yb, zd, wc\}$ is a stable matching.

Men $\{x, y, z, w\}$ Women $\{a, b, c, d\}$ x: a > b > c > da: z > x > y > wy: a > c > b > db: y > w > x > zz: c > d > a > bc: w > x > y > zw: c > b > a > dd: x > y > z > w

Matchings in General Graphs

Perfect matchings

- K_{2n} , C_{2n} , P_{2n} have perfect matchings
- Corollary (3.1.13, W; 2.1.3, D) Every k-regular (k > 0) bipartite graph has a perfect matching
- Theorem(1.58, H) If G is a graph of order 2n such that $\delta(G) \ge n$, then G has a perfect matching

Theorem (1.22, H, Dirac) Let G be a graph of order $n \ge 3$. If $\delta(G) \ge n/2$, then G is Hamiltonian

Tutte's Theorem (TONCAS)

- Let q(G) be the number of connected components with odd order
- Theorem (1.59, H; 2.2.1, D; 3.3.3, W) Let G be a graph of order $n \ge 2$. G has a perfect matching $\Leftrightarrow q(G - S) \le |S|$ for all $S \subseteq V$

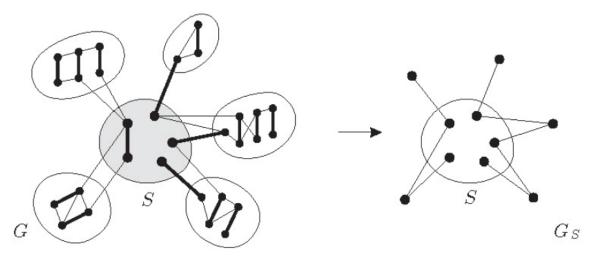


Fig. 2.2.1. Tutte's condition $q(G-S) \leq |S|$ for q = 3, and the contracted graph G_S from Theorem 2.2.3.

Petersen's Theorem

• Theorem (1.60, H; 2.2.2, D; 3.3.8, W) Every bridgeless, 3-regular graph contains a perfect matching

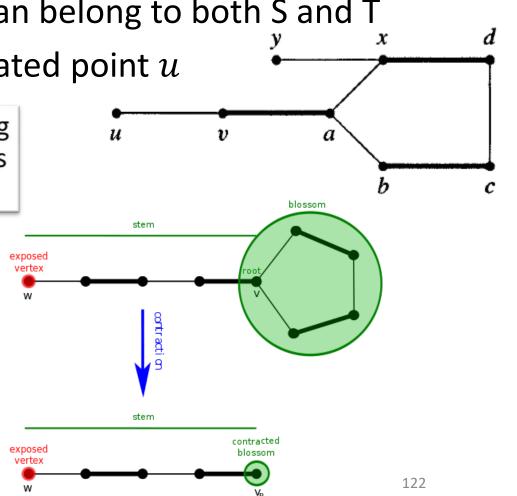
> Theorem (1.59, H; 2.2.1, D; 3.3.3, W) Let G be a graph of order $n \ge 2$. G has a perfect matching $\Leftrightarrow q(G - S) \le |S|$ for all $S \subseteq V$

Find augmenting paths in general graphs

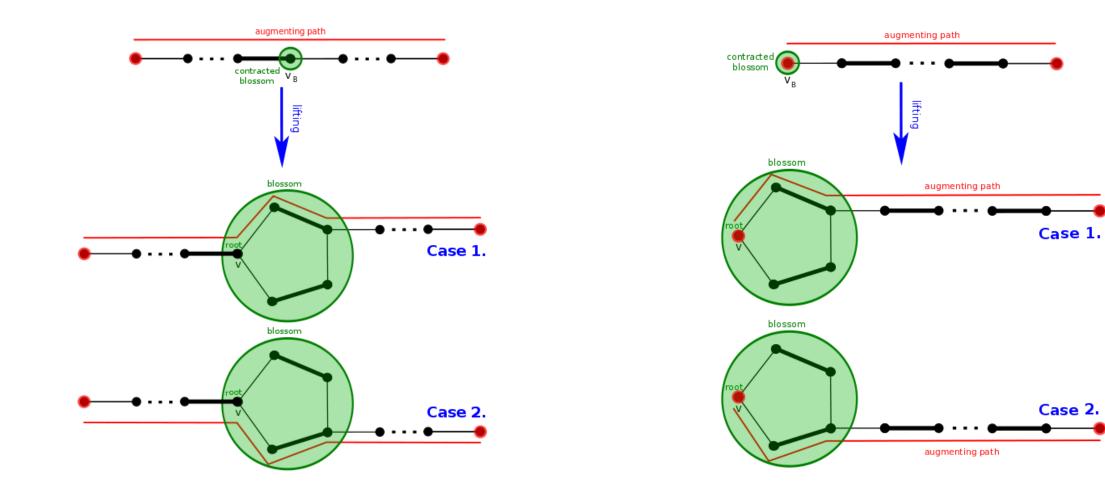
- Different from bipartite graphs, a vertex can belong to both S and T
- Example: How to explore from M-unsaturated point u

Theorem (3.1.10, W; 1.50, H; Berge 1957) A matching M in a graph G is a maximum matching in $G \Leftrightarrow G$ has no M-augmenting path

• Flower/stem/blossom



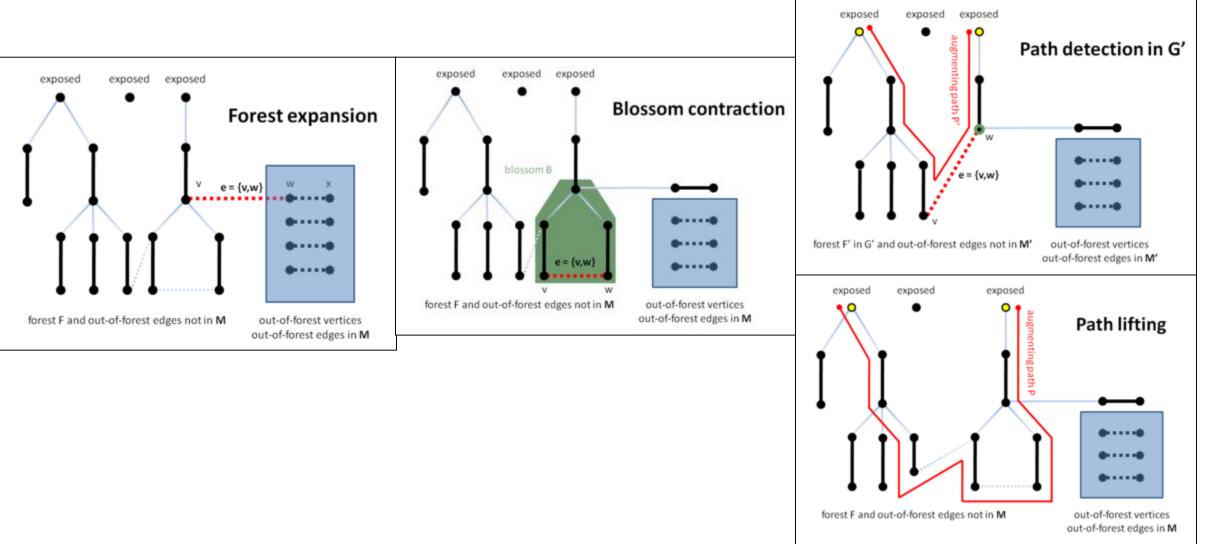
Lifting



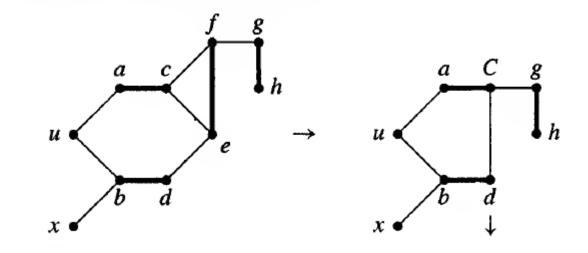
Edmonds' blossom algorithm (3.3.17, W)

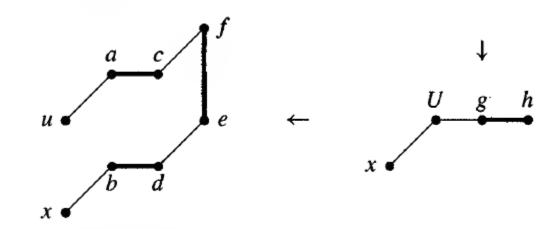
- Input: A graph G, a matching M in G, an M-unsaturated vertex u
- Idea: Explore M-alternating paths from *u*, recording for each vertex the vertex from which it was reached, and contracting blossoms when found
 - Maintain sets S and T analogous to those in Augmenting Path Algorithm, with S consisting of u and the vertices reached along saturated edges
 - Reaching an unsaturated vertex yields an augmentation.
- Initialization: $S = \{u\}$ and $T = \emptyset$
- Iteration: If S has no unmarked vertex, stop; there is no M-augmenting path from u
 - Otherwise, select an unmarked $v \in S$. To explore from v, successively consider each $y \in N(v)$ s.t. $y \notin T$
 - If y is unsaturated by M, then trace back from y (expanding blossoms as needed) to report an M-augmenting u, y-path
 - If $y \in S$, then a blossom has been found. Suspend the exploration of v and contract the blossom, replacing its vertices in S and T by a single new vertex in S. Continue the search from this vertex in the smaller graph.
 - Otherwise, y is matched to some w by M. Include y in T (reached from v), and include w in S (reached from y)
 - After exploring all such neighbors of v, mark v and iterate

Illustration

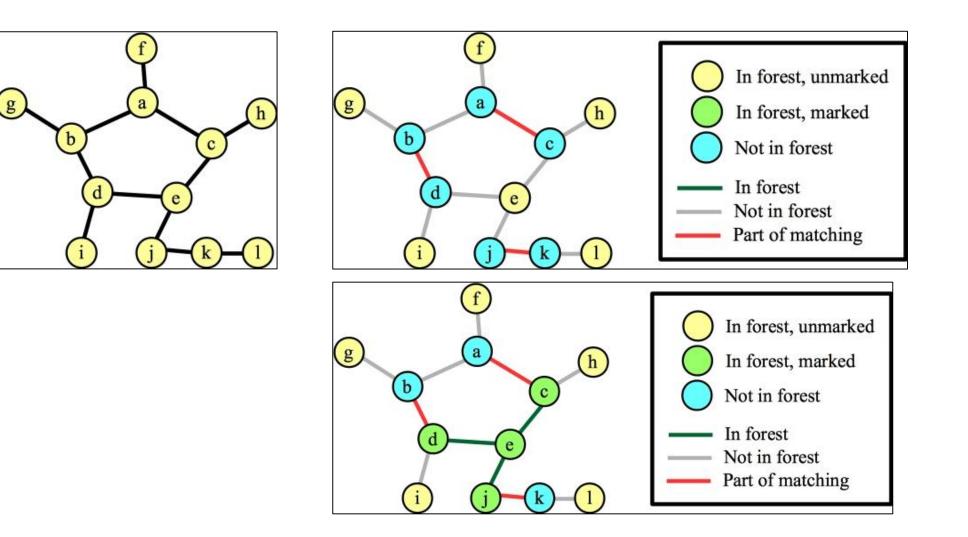


Example

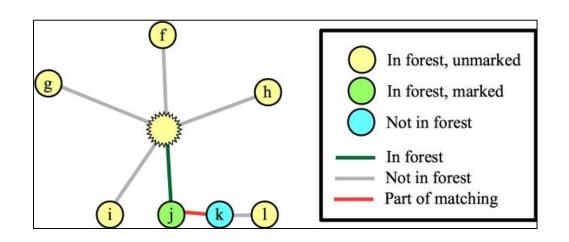


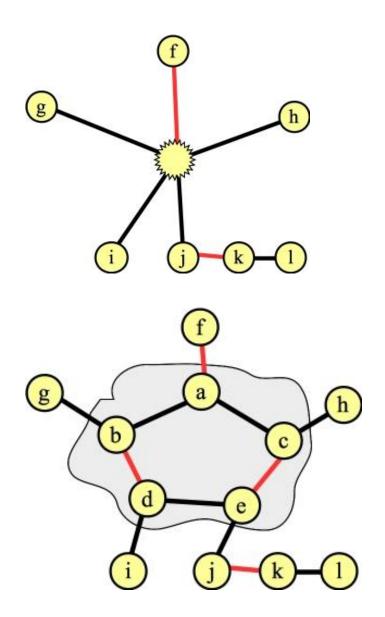


Example 2



Example 2 (cont.)





Lecture 6: More on Connectivity

Shuai Li

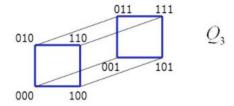
John Hopcroft Center, Shanghai Jiao Tong University

https://shuaili8.github.io

https://shuaili8.github.io/Teaching/CS445/index.html

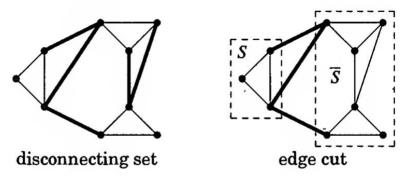
Vertex cut set and connectivity

- A proper subset S of vertices is a vertex cut set if the graph G S is disconnected
- The connectivity, $\kappa(G)$, is the minimum size of a vertex set S of G such that G S is disconnected or has only one vertex
 - The graph is k-connected if $k \leq \kappa(G)$
- $\kappa(K_n) := n 1$
- If G is disconnected, $\kappa(G) = 0$
 - \Rightarrow A graph is connected $\Leftrightarrow \kappa(G) \ge 1$
- If G is connected, non-complete graph of order n, then $1 \le \kappa(G) \le n-2$



- For convention, $\kappa(K_1) = 0$
- Example (4.1.3, W) For k-dimensional cube $Q_k = \{0,1\}^k$, $\kappa(Q_k) = k$

Edge-connectivity



- A disconnecting set of edges is a set F ⊆ E(G) such that G − F has more than one component
 - A graph is *k*-edge-connected if every disconnecting set has at least *k* edges
 - The edge-connectivity of G, written λ(G), is the minimum size of a disconnecting set
- Given $S, T \subseteq V(G)$, we write [S, T] for the set of edges having one endpoint in S and the other in T
 - An edge cut is an edge set of the form [*S*, *S^c*] where *S* is a nonempty proper subset of *V*(*G*)
- Every edge cut is a disconnecting set, but not vice versa
- Remark (4.1.8, W) Every minimal disconnecting set of edges is an edge cut

Connectivity and edge-connectivity

• Proposition (1.4.2, D) If G is non-trivial, then $\kappa(G) \leq \lambda(G) \leq \delta(G)$

• If
$$\delta(G) \ge n-2$$
, then $\kappa(G) = \delta(G)$

that is $\kappa(G) = \lambda(G) = \delta(G)$

• Theorem (4.1.11, W) If G is a 3-regular graph, then $\kappa(G) = \lambda(G)$

Properties of edge cut

- When $\lambda(G) < \delta(G)$, a minimum edge cut cannot isolate a vertex
- Similarly for (any) edge cut
- Proposition (4.1.12, W) If S is a set of vertices in a graph G, then $|[S, S^{c}]| = \sum_{v \in S} d(v) - 2e(G[S])$
- Corollary (4.1.13, W) If G is a simple graph and $|[S, S^c]| < \delta(G)$, then $|S| > \delta(G)$
 - |S| must be much larger than a single vertex

Blocks

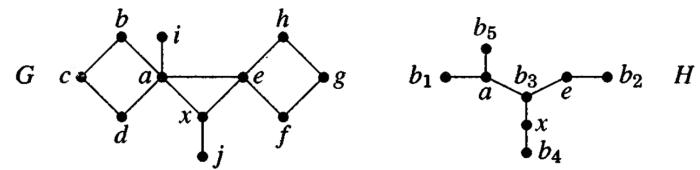
- A block of a graph G is a maximal connected subgraph of G that has no cut-vertex. If G itself is connected and has no cut-vertex, then G is a block
- Example
- Proposition (1.2.14, W)
- An edge e is a bridge $\Leftrightarrow e$ lies on no cycle of G
 - Or equivalently, an edge e is not a bridge $\Leftrightarrow e$ lies on a cycle of G
- An edge of a cycle cannot itself be a block
 - An edge is block \Leftrightarrow it is a bridge
 - The blocks of a tree are its edges
- If a block has more than two vertices, then it is 2-connected
 - The blocks of a loopless graph are its isolated vertices, bridges, and its maximal 2-connected subgraphs

Intersection of two blocks

- Proposition (4.1.19, W) Two blocks in a graph share at most one vertex
 - When two blocks share a vertex, it must be a cut-vertex
- Every edge is a subgraph with no cut-vertex and hence is in a block. Thus blocks in a graph decompose the edge set

Block-cutpoint graph

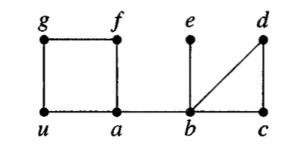
• The block-cutpoint graph of a graph G is a bipartite graph H in which one partite set consists of the cut-vertices of G, and the other has a vertex b_i for each block B_i of G. We include vb_i as an edge of $H \Leftrightarrow$ $v \in B_i$



• (Ex34, S4.1, W) When G is connected, its block-cutpoint graph is a tree

Depth-first search (DFS)

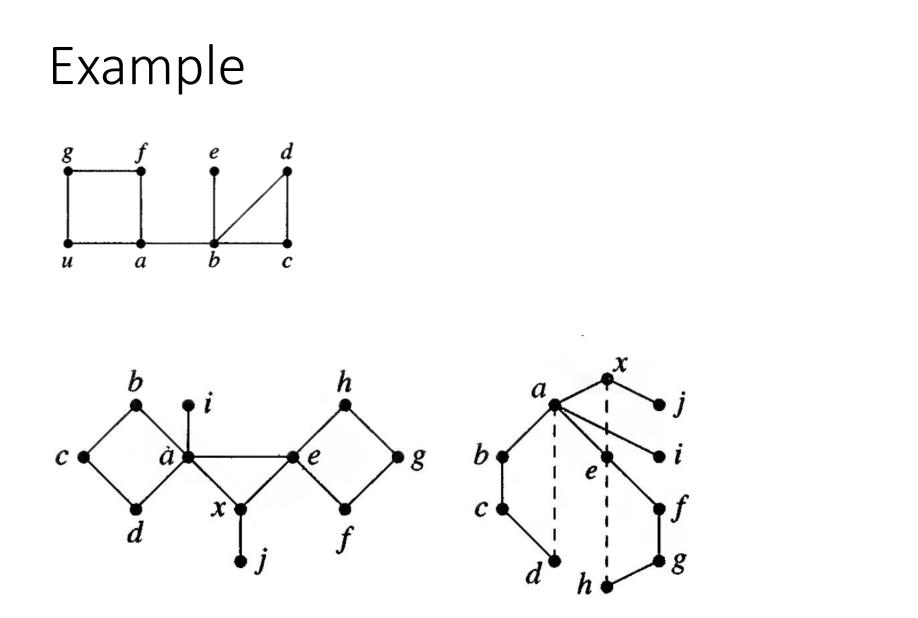
• Depth-first search



• Lemma (4.1.22, W) If T is a spanning tree of a connected graph grown by DFS from u, then every edge of G not in T consists of two vertices v, w such that v lies on the u, w-path in T

Finding blocks by DFS

- Input: A connected graph G
- Idea: Build a DFS tree T of G, discarding portions of T as blocks are identified. Maintain one vertex called ACTIVE
- Initialization: Pick a root $x \in V(H)$; make x ACTIVE; set $T = \{x\}$
- Iteration: Let v denote the current active vertex
 - If v has an unexplored incident edge vw, then
 - If $w \notin V(T)$, then add vw to T, mark vw explored, make w ACTIVE
 - If $w \in V(T)$, then w is an ancestor of v; mark vw explored
 - If v has no more unexplored incident edges, then
 - If $v \neq x$ and w is a parent of v, make w ACTIVE. If no vertex in the current subtree T' rooted at v has an explored edge to an ancestor above w, then $V(T') \cup \{w\}$ is the vertex set of a block; record this information and delete V(T')
 - if v = x, terminate



Strong orientation

- Theorem (2.5, L; 4.2.14, W; Robbins 1939) A graph has a strong orientation, i.e. an orientation that is a strongly connected digraph ⇔ it is 2-edge-connected
 - A directed graph is strongly connected if for every pair of vertices (*v*, *w*), there is a directed path from *v* to *w*
 - Proposition (2.4, L) Let xy ∈ T which is not a bridge in G and x is a parent of y. Then there exists an edge in G but not in T joining some descendant a of y and some ancestor b of x
 - The blocks of a loopless graph are its isolated vertices, bridges, and its maximal 2-connected subgraphs

Lemma (4.1.22, W) If T is a spanning tree of a connected graph grown by DFS from u, then every edge of G not in T consists of two vertices v, w such that v lies on the u, w-path in T